

# MTH 261

## LINEAR ALGEBRA

### SPRING 2017

#### Linear Transformations

Find partners, and follow the instructions. You will not turn this in, but you must be working diligently to get attendance credit.

1. Let  $A = \begin{bmatrix} 1 & -2 & 3 \\ 0 & 1 & -3 \\ 2 & -5 & 6 \end{bmatrix}$  and  $\vec{b} = \begin{bmatrix} -6 \\ -4 \\ -5 \end{bmatrix}$ . Is  $\vec{b}$  in the <sup>range</sup> image of  $T_A$ ?

$$T_A: \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

Maybe



If...  $A\vec{x} = \vec{b}$  has a solution?

$$\left[ \begin{array}{ccc|c} 1 & -2 & 3 & -6 \\ 0 & 1 & -3 & -4 \\ 2 & -5 & 6 & -5 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & -2 & 3 & -6 \\ 0 & 1 & -3 & -4 \\ 0 & -1 & 0 & 7 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & -2 & 3 & -6 \\ 0 & 1 & -3 & -4 \\ 0 & 0 & -3 & 3 \end{array} \right]$$

$$\rightarrow \left[ \begin{array}{ccc|c} 1 & -2 & 0 & -3 \\ 0 & 1 & 0 & -7 \\ 0 & 0 & 1 & -1 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} 1 & 0 & 0 & -17 \\ 0 & 1 & 0 & -7 \\ 0 & 0 & 1 & -1 \end{array} \right]$$

Yes, it does

have a solution. So yes,

$\vec{b}$  is in the image of  $T_A$ .

output  
vectors have  
4 entries

2. Let  $A = \begin{bmatrix} 1 & -3 & 2 \\ 3 & -8 & 8 \\ 0 & 1 & 2 \\ 1 & 0 & 8 \end{bmatrix}$ ,  $\vec{b} = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$ , and  $\vec{c} = \begin{bmatrix} 1 \\ 6 \\ 3 \\ 10 \end{bmatrix}$ . Is  $\vec{b}$  in the image of  $T_A$ ? Is  $\vec{c}$  in the image

of  $T_A$ ? What is  $T_A(\vec{b})$ ?

No!

$\vec{b}$  is in  $\mathbb{R}^3$ , but  
the codomain is  $\mathbb{R}^4$

$$\left[ \begin{array}{ccc|c} 1 & -3 & 2 & 1 \\ 3 & -8 & 8 & 6 \\ 0 & 1 & 2 & 3 \\ 1 & 0 & 8 & 10 \end{array} \right] \xrightarrow{\text{RREF}} \left[ \begin{array}{ccc|c} 1 & 0 & 8 & 10 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

system is consistent.

There is a solution to  $A\vec{x} = \vec{c}$

So  $\vec{c}$  is in the image of  $T_A$ .

$$T_A(\vec{b}) = A \cdot \vec{b} = 2 \begin{bmatrix} 1 \\ 3 \\ 0 \\ 1 \end{bmatrix} + 1 \cdot \begin{bmatrix} -3 \\ -8 \\ 1 \\ 0 \end{bmatrix} - 3 \begin{bmatrix} 2 \\ 8 \\ 2 \\ 8 \end{bmatrix} = \begin{bmatrix} -7 \\ -26 \\ -5 \\ -22 \end{bmatrix}$$

3. Define  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$  by  $T(\vec{x}) = \begin{bmatrix} x_2 - x_1 \\ 3x_1 + x_2 \\ x_1 \end{bmatrix}$ . Is  $T$  a linear transformation? If so, prove it according to the definition of a linear transformation. If not, show why not.

$$T(\vec{u} + \vec{v}) \stackrel{?}{=} T(\vec{u}) + T(\vec{v})$$

$$T\left(\begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \end{bmatrix}\right) \stackrel{?}{=} \begin{bmatrix} u_2 + v_2 - (u_1 + v_1) \\ 3(u_1 + v_1) + (u_2 + v_2) \\ u_1 + v_1 \end{bmatrix} \stackrel{?}{=} \begin{bmatrix} u_2 - u_1 \\ 3u_1 + u_2 \\ u_1 \end{bmatrix} + \begin{bmatrix} v_2 - v_1 \\ 3v_1 + v_2 \\ v_1 \end{bmatrix} \stackrel{?}{=} \begin{bmatrix} u_2 - u_1 + v_2 - v_1 \\ 3u_1 + u_2 + 3v_1 + v_2 \\ u_1 + v_1 \end{bmatrix} \stackrel{?}{=} \begin{bmatrix} u_2 - u_1 \\ 3u_1 + u_2 \\ u_1 \end{bmatrix} + \begin{bmatrix} v_2 - v_1 \\ 3v_1 + v_2 \\ v_1 \end{bmatrix}$$

$$T(c\vec{u}) \stackrel{?}{=} cT(\vec{u})$$

$$T\left(\begin{bmatrix} cu_1 \\ cu_2 \end{bmatrix}\right) \stackrel{?}{=} c \cdot \begin{bmatrix} u_2 - u_1 \\ 3u_1 + u_2 \\ u_1 \end{bmatrix}$$

4. Define  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$  by  $T(\vec{x}) = \begin{bmatrix} x_3 + 1 \\ x_1 - x_2 \end{bmatrix}$ . Is  $T$  a linear transformation? If so, prove it according to the definition of a linear transformation. If not, show why not.

$$T(\vec{0}) = T\left(\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$T(\vec{0}) = \text{not } \vec{0}$$

$\Rightarrow T$  is not linear.

5. Define  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  by  $T(\vec{x}) = \begin{bmatrix} |x_1| \\ x_1 + x_2 \\ \sin(x_3) \end{bmatrix}$ . Is  $T$  a linear transformation? If so, prove it according to the definition of a linear transformation. If not, show why not.

Very suspicious... suspect it's not linear.

Note  $T\left(-1 \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) \stackrel{?}{=} -1 \cdot T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right)$

$$T\left(\begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}\right) \stackrel{?}{=} -1 \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \stackrel{?}{=} \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix}$$

No!