

Vector Spaces that emerge from matrices (and affiliated vocabulary)

Suppose that A is an $n \times m$ matrix and that B is the reduced echelon equivalent of A . Then:

- The **rank** of A is the number of non-zero rows in B .
- The **column space** of A is the set of all linear combinations of the columns of A . The column space of A is a subspace of \mathbb{R}^n and its dimension is equal to $\text{rank}(A)$. The pivot columns of A form a basis for $\text{col}(A)$. *This basis comes from the original matrix.*
- The **row space** of A is the set of all linear combinations of the rows of A . The row space of A is a subspace of \mathbb{R}^m and its dimension is equal to $\text{rank}(A)$. The non-zero rows of B form a basis for $\text{row}(A)$. *This basis comes from the RREF matrix.*
- The **null space** of A is the set of all solutions to the equation $A\vec{x} = \vec{0}$. The null space of A is a subspace of \mathbb{R}^m and its dimension is equal to $m - \text{rank}(A)$. One way to find a basis for $\text{nul}(A)$ is to create vectors from the general solution to $A\vec{x} = \vec{0}$ where one vector is created for each free-variable by letting that free variable have a non-zero value whilst all the other free-variables are set to zero.

$$\dim(\text{row space}) + \dim(\text{null space}) = \# \text{ of columns.}$$

$\text{rank} \leftarrow$ Also the dimension of the column space.

Example

Consider $M = \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 0 & 5 \\ 0 & 1 & -1 & 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 1 & 0 & 5 & -2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$. *3* State the correct number in each of the blanks below.

The rank of M is 3.

The column space of M is a 3-dimensional subspace of $\mathbb{R}^{\underline{4}}$.

The row space of M is a 3-dimensional subspace of $\mathbb{R}^{\underline{7}}$.

The null space of M is a 4-dimensional subspace of $\mathbb{R}^{\underline{7}}$.

Example

Consider $M = \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 0 & 5 \\ 0 & 1 & -1 & 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 1 & 0 & 5 & -2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$. Answer each of the following questions about M .

State a basis for $\text{row}(M)$.

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 2 \\ 0 \\ 0 \\ 0 \\ 5 \end{bmatrix}^T, \begin{bmatrix} 0 \\ 1 \\ -1 \\ 0 \\ 0 \\ 0 \\ 3 \end{bmatrix}^T, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 5 \\ -2 \end{bmatrix}^T \right\}$$

True or false? The stated basis for $\text{row}(M)$ is also a basis for the row space of any matrix that is row equivalent to M . Justify your answer!

True. Row Equivalent matrices are produced via

- (1) Swapping rows (contextually irrelevant)
- (2) Replacing rows with linear combinations of existing rows.

State a basis for $\text{col}(M)$.

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} \right\}$$

True or false? The stated basis for $\text{col}(M)$ is also a basis the column space for any matrix that is row equivalent to M . Justify your answer!

Nothing falser could be. To wit:

$$M: R_3 + R_4 \rightarrow R_4 \quad \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 0 & 5 \\ 0 & 1 & -1 & 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 1 & 0 & 5 & -2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \text{ (call this } M_{\text{new}})$$

$\begin{bmatrix} 5 \\ -2 \\ -2 \end{bmatrix} \in \text{col}(M_{\text{new}})$, but obviously $\begin{bmatrix} 5 \\ -2 \\ -2 \end{bmatrix}$ is not in the span stated in the last question.

Example

Consider $M = \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 0 & 5 \\ 0 & 1 & -1 & 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 1 & 0 & 5 & -2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$. Answer each of the following questions about M .

State a basis for $\text{nul}(M)$.

"Scratch work"

$$M\vec{x} = \vec{0}$$

$$x_1 = -2x_3 - 5x_7$$

$$x_2 = x_3 - 3x_7$$

$$x_4 = -5x_6 + 2x_7$$

x_3, x_5, x_6, x_7 are free

Basis: $\left\{ \begin{bmatrix} -2 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ -3 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

$x_3=1 \quad x_5=1 \quad x_6=1 \quad x_7=1$

True or false? The stated basis for $\text{nul}(M)$ is also a basis for the null space of any matrix that is row equivalent to M . Justify your answer!

Nothing could be truer. This is the entire basis of this class. Adding a non-zero multiple of two sides of two equations from a system of equations does not change the solution set.

$A\vec{x} = \vec{0}$
 $\left[A \mid \begin{smallmatrix} 0 \\ 0 \\ 0 \end{smallmatrix} \right]$ Row reduction

Example

Find bases for $\text{row}(A)$, $\text{col}(A)$, and $\text{nul}(A)$ where $A = \begin{bmatrix} 2 & -4 & -3 & 17 & 5 \\ -1 & 2 & 3 & -13 & -4 \\ 4 & -8 & 1 & 13 & 3 \end{bmatrix}$.

$$A \sim \begin{bmatrix} 1 & -2 & 0 & 4 & 1 \\ 0 & 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Basis for row space: $\left\{ \begin{bmatrix} 1 \\ -2 \\ 0 \\ 4 \\ 1 \end{bmatrix}^T, \begin{bmatrix} 0 \\ 0 \\ 1 \\ -3 \\ -1 \end{bmatrix}^T \right\}$ } rank = 2

Basis for column space: $\left\{ \begin{bmatrix} 2 \\ -1 \\ 4 \end{bmatrix}, \begin{bmatrix} -3 \\ 3 \\ 1 \end{bmatrix} \right\}$

Basis for null space: $\left\{ \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -4 \\ 0 \\ 3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ } dimension add to 5
 \uparrow not columns

What are bases for the kernel and range of the linear transformation $T(\vec{x}) = A\vec{x}$ where $A = \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}$.

What does this imply must be true about A^2 .

Nullspace: $A\vec{x} = \vec{0}$, $x_1 = x_2$: Basis: $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$

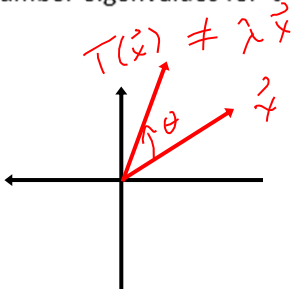
Range: $c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ -1 \end{bmatrix}$: Basis: $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \xrightarrow{T} \underbrace{k \begin{bmatrix} 1 \\ 1 \end{bmatrix}}_{\text{in the null space of } A \text{ (kernel of } T)} \xrightarrow{T} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$T(T(\vec{x})) = \vec{0} \Rightarrow A(A\vec{x}) = \vec{0} \quad \forall \vec{x}$$

$$\Rightarrow A^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Explain geometrically why the rotation matrix $R = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$ cannot possibly have any real number eigenvalues for $0 < \theta < \pi$.



If λ was an eigenvalue for R , for some \vec{x} we'd have $R\vec{x} = \lambda\vec{x}$

QED

Let $A = \begin{bmatrix} 1 & 2 & 1 & 4 \\ 2 & 1 & 5 & -2 \\ -2 & 2 & -8 & 0 \\ 3 & 2 & 7 & 10 \end{bmatrix}$ and note that $A \sim \begin{bmatrix} 1 & 0 & 3 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$. Find a basis for each of the

following vector spaces without actually transposing the matrix A . In each case, write a few words so that the rationale for whatever action/conclusion you take/make is clear.

a. $\text{null}(A^T)^\perp$

$$\begin{aligned} \text{null}(A^T)^\perp &= \text{row}(A^T) \\ &= \text{col}(A) \end{aligned}$$

$$\text{Basis: } \left\{ \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{3} \end{bmatrix}, \begin{bmatrix} 2 \\ \frac{1}{2} \\ 2 \end{bmatrix}, \begin{bmatrix} -\frac{4}{3} \\ \frac{1}{3} \end{bmatrix} \right\}$$

b. $\text{col}(A^T)^\perp$

$$\begin{aligned} \text{col}(A^T)^\perp &= \text{row}(A)^\perp \\ &= \text{null}(A) \end{aligned}$$

$$\text{Basis: } \left\{ \begin{bmatrix} -3 \\ 1 \\ 0 \\ 1 \end{bmatrix} \right\}$$