

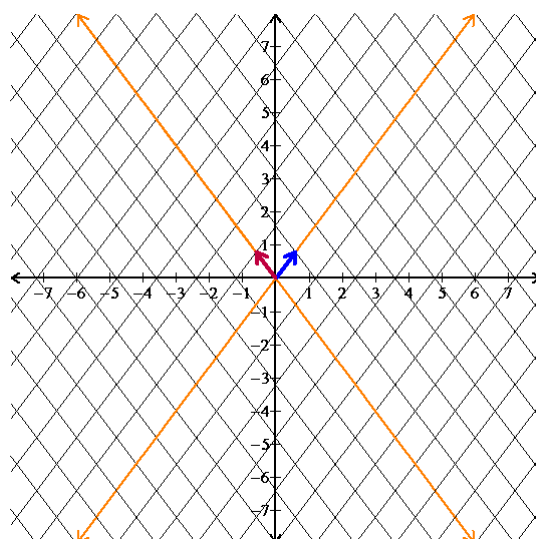
**Example 9.1**

Consider the  $\mathbb{R}^2$  basis  $\beta = \left\{ \begin{bmatrix} 3 \\ -1 \end{bmatrix}, \begin{bmatrix} -2 \\ 5 \end{bmatrix} \right\}$ . Answer each of the following questions relative to  $\beta$ .

- a. Determine  $\vec{x}$  if  $[\vec{x}]_\beta = \begin{bmatrix} -4 \\ 7 \end{bmatrix}$ .      b. Determine  $[\vec{x}]_\beta$  if  $\vec{x} = \begin{bmatrix} 26 \\ -39 \end{bmatrix}$ .

**Example 9.2**

Let  $\vec{c}_1 = \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}$ ,  $\vec{c}_2 = \begin{bmatrix} -3/5 \\ 4/5 \end{bmatrix}$ ,  $\vec{x} = \begin{bmatrix} 6 \\ 0 \end{bmatrix}$ , and  $\gamma = \{ \vec{c}_1, \vec{c}_2 \}$ . Find the change-of-basis matrix from the standard basis to  $\gamma$  and use that matrix to find  $[\vec{x}]_\gamma$ .

**Example 9.3**

Let  $\beta = \left\{ \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix} \right\}$  and  $\gamma = \left\{ \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} \right\}$ . Find the transition matrix from  $\beta$  to  $\gamma$  and

use that to find  $[\vec{x}]_\gamma$  where  $[\vec{x}]_\beta = \begin{bmatrix} 3 \\ 2 \\ -4 \end{bmatrix}$ . Verify the result!

**Theorem 9.1 and Definition 9.1**

Suppose that the set  $\beta = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_n\}$  forms a basis for  $\mathbb{R}^n$ . Then for each vector  $\vec{x}$  in  $\mathbb{R}^n$ , there exists a unique set of constants,  $c_1 - c_n$  such that  $\vec{x} = c_1 \vec{b}_1 + c_2 \vec{b}_2 + \dots + c_n \vec{b}_n$ . The constants  $c_1 - c_n$  are called the  $\beta$  – coordinates of  $\vec{x}$  and this relationship is symbolized as:

$$[\vec{x}]_{\beta} = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}.$$

**Theorem 9.2**

Suppose that  $\beta$  and  $\gamma$  are both bases for  $\mathbb{R}^n$  and that  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$  by the rule  $T([\vec{x}]_{\beta}) = [\vec{x}]_{\gamma}$ . Then  $T$  is a one-to-one, onto linear transformation and, as such, there exists a matrix  $\underset{\gamma \leftarrow \beta}{P}$  with the property

that  $[\vec{x}]_{\gamma} = \underset{\gamma \leftarrow \beta}{P} [\vec{x}]_{\beta}$ .

**Theorem 9.3**

Suppose that  $\beta$  and  $\gamma$  are two ordered bases for  $\mathbb{R}^n$ ,  $\vec{x} \in \mathbb{R}^n$ , and the components of  $\vec{x}$  relative to  $\beta$  are known. Then the components of  $\vec{x}$  relative to  $\gamma$  can be determined by the equation

$$[\vec{x}]_{\gamma} = \underset{\gamma \leftarrow \beta}{P} [\vec{x}]_{\beta} \text{ where } \underset{\gamma \leftarrow \beta}{P} \text{ is called the } \underline{\text{change-of-coordinates matrix}} \text{ from } \beta \text{ to } \gamma.$$

When working in  $\mathbb{R}^n$  we can find  $\underset{\gamma \leftarrow \beta}{P}$  using Gaussian elimination. Specifically:

$$[\gamma \mid \beta] \xrightarrow{\text{RREF}} \left[ I_n \mid \underset{\gamma \leftarrow \beta}{P} \right]$$

Please note that this implies that if  $\beta$  is the standard ordered basis for  $\mathbb{R}^n$ , then the change-of-basis matrix to  $\gamma$  is simply  $\gamma^{-1}$ .