

Example 3.1

$$a. \quad \begin{cases} 2x_1 + 4x_2 = 3x_2 - 7x_1 \\ 5x_1 - 6 = 2x_2 - 6 \end{cases}$$

$$\Rightarrow \begin{cases} 9x_1 + x_2 = 0 \\ 5x_1 - 2x_2 = 0 \end{cases}$$

\therefore The system is homogeneous

$$b. \quad 4 \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + 2 \begin{bmatrix} x_1 \\ 5 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{cases} 4x_1 + 2x_1 = 0 \\ 4x_2 = -10 \\ 4x_3 + 2x_3 = 0 \end{cases}$$

not homogeneous

c. Aw, a kitty cat!

3.2

$$\begin{bmatrix} 2 & -3 & 7 \\ -3 & 1 & -7 \\ 4 & 0 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{cases} 2x_1 - 3x_2 + 7x_3 = 0 \\ -3x_1 + x_2 - 7x_3 = 0 \\ 4x_1 + 8x_3 = 0 \end{cases}$$

$$\left[\begin{array}{ccc|c} 2 & -3 & 7 & 0 \\ -3 & 1 & -7 & 0 \\ 4 & 0 & 8 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 2 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

\therefore The general solution is $\begin{cases} x_1 = -2x_3 \\ x_2 = x_3 \\ x_3 \text{ is free} \end{cases}$

\therefore Solutions can be written in

vector form as $\begin{bmatrix} -2x_3 \\ x_3 \\ x_3 \end{bmatrix}$

which in turn is equivalent

to $x_3 \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$

\therefore The solution set is $\text{Span} \left(\left\{ \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix} \right\} \right)$

This solution set is a line through the origin.

Ex 3.3 //

$$\begin{bmatrix} 2 & -3 & 7 \\ -3 & 1 & -7 \\ 4 & 0 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 9 \\ -10 \\ 12 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 2 & -3 & 7 & 9 \\ -3 & 1 & -7 & -10 \\ 4 & 0 & 8 & 12 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 2 & 3 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

general solution:
$$\begin{cases} x_1 = -2x_3 + 3 \\ x_2 = x_3 - 1 \\ x_3 \text{ is free} \end{cases}$$

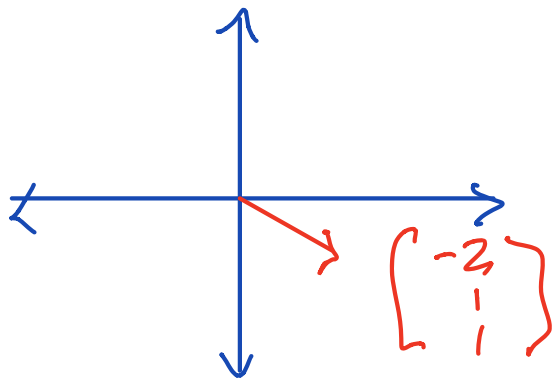
$$\therefore \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2x_3 + 3 \\ x_3 - 1 \\ x_3 \end{bmatrix}$$

$$= \begin{bmatrix} -2x_3 \\ x_3 \\ x_3 \end{bmatrix} + \begin{bmatrix} 3 \\ -1 \\ 0 \end{bmatrix}$$

$$= x_3 \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 3 \\ -1 \\ 0 \end{bmatrix}$$

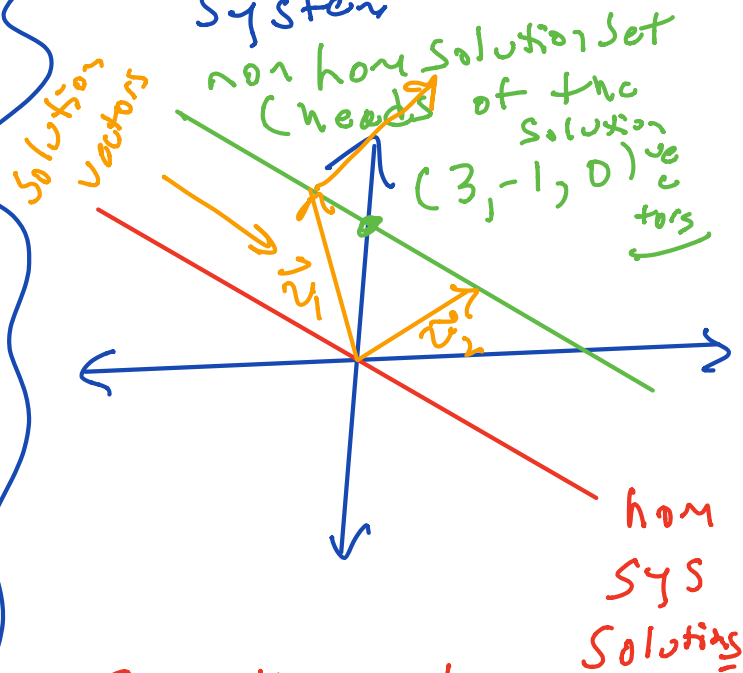
This is the solution set to the analogous homogeneous system shifted (same coefficients) so that it passes through the point $(3, -1, 0)$ rather than the origin.

Homogeneous system
Solution set.



If we add two multiples of this solution vector we get another multiple of this solution vector. We say that this solution set is closed over scalar multiplication and vector addition.

non homogeneous
System



Solutions to the hom system can be drawn onto the red line.

Solutions to the non-homogeneous system cannot be drawn onto any common line.

The head of $\vec{v}_1 + \vec{v}_2$ does not lie on the green line. Solution sets to non-homogeneous systems are not closed over either scalar multiplication or vector addition.

Non homogeneous systems do not have spanning sets for their solution set.

3.4 //

$$\begin{cases} 3x_1 - 12x_2 - 6x_3 = 0 \text{ (homogeneous)} \end{cases}$$

The general solution is

$$\begin{cases} x_1 = 4x_2 + 2x_3 \\ x_2 \text{ is free} \\ x_3 \text{ is free} \end{cases}$$

So solutions can be written as:

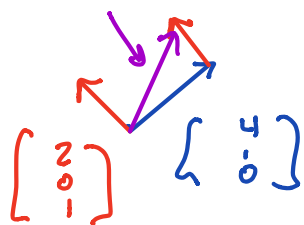
$$\begin{aligned} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} &= \begin{bmatrix} 4x_2 + 2x_3 \\ x_2 \\ x_3 \end{bmatrix} \\ &= \begin{bmatrix} 4x_2 \\ x_2 \\ 0 \end{bmatrix} + \begin{bmatrix} 2x_3 \\ 0 \\ x_3 \end{bmatrix} \\ &= x_2 \begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \end{aligned}$$

Every vector in the solution set can be written as a linear combination

of $\begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$ and any linear combination of those two vectors is in the solution set.

The solution set is $\text{Span}\left(\left\{\begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}\right\}\right)$

$\begin{bmatrix} 6 \\ 1 \\ 1 \end{bmatrix}$ is also in the solution set



Collectively, this solution set forms a plane through the origin

$$\begin{cases} 3x_1 - 12x_2 - 6x_3 = -15 \end{cases} \text{ (nonhomogeneous system)}$$

Solution can be written as

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} + \begin{bmatrix} -5 \\ 0 \\ 0 \end{bmatrix}$$

This is the homogeneous solution shifted from the origin to the point $(-5, 0, 0)$, but it only shifts the heads of the vectors. The vectors themselves do not lie on a common plane. Two solution vectors add to a not-a-solution vector.

3.5)
$$A = \begin{bmatrix} 2 & -3 & 1 \\ -3 & 4 & -2 \\ 3 & -5 & 1 \end{bmatrix}$$

The column vectors of A are linearly dependent if and only if:

$$x_1 \begin{bmatrix} 2 \\ -3 \\ 3 \end{bmatrix} + x_2 \begin{bmatrix} -3 \\ 4 \\ -5 \end{bmatrix} + x_3 \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

has non-trivial solutions (not all x_1, x_2, x_3 equal to zero).

$$\left[\begin{array}{ccc|ccc} 2 & -3 & 1 & 0 & 0 & 0 \\ -3 & 4 & -2 & 0 & 0 & 0 \\ 3 & -5 & 1 & 0 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 2 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right]$$

QED

QED (Quod Erat Deductum)
It means "it has been demonstrated"
It's written in lieu of a formal conclusion.

In this case it's appropriate because the $\text{RREF}(A)$ indicates the presence of free variables in the solution set.

which means that the vector equation has "infinitely many solutions", all but one of which is non-trivial.

== The general solution is $\begin{cases} x_1 = -2x_3 \\ x_2 = -x_3 \\ x_3 \text{ is free} \end{cases}$

So an explicit illustration of the linear dependency is

$$-2 \begin{bmatrix} 2 \\ -3 \\ 3 \end{bmatrix} + (-1) \begin{bmatrix} -3 \\ 4 \\ -5 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Ex 3.6

$$A = \begin{bmatrix} 2 & a & -2 \\ 3 & a & 3 \\ -1 & -2 & a \end{bmatrix}$$

The column vectors of A are linearly independent iff the only solution to

$$x_1 \begin{bmatrix} 2 \\ 3 \\ -1 \end{bmatrix} + x_2 \begin{bmatrix} a \\ a \\ -2 \end{bmatrix} + x_3 \begin{bmatrix} -2 \\ 3 \\ a \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

is $\begin{cases} x_1 = 0 \\ x_2 = 0 \\ x_3 = 0 \end{cases}$ (trivial solution)

$$\left[\begin{array}{ccc|c} 2 & a & -2 & 0 \\ 3 & a & 3 & 0 \\ -1 & -2 & a & 0 \end{array} \right] \xrightarrow{R_1 \leftrightarrow R_3} \left[\begin{array}{ccc|c} -1 & -2 & a & 0 \\ 3 & a & 3 & 0 \\ 2 & a & -2 & 0 \end{array} \right]$$

$$\begin{aligned}
& 3R_1 + R_2 \rightarrow R_2 \\
& 2R_1 + R_3 \rightarrow R_3 \\
& -\frac{a-4}{a-6} R_2 + R_3 \rightarrow R_3
\end{aligned}
\begin{bmatrix} -1 & -2 & a & 10 \\ 0 & a-6 & 3a+3 & 0 \\ 0 & a-4 & 2a-2 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & -2 & a & 10 \\ 0 & a-6 & 3a+3 & 0 \\ 0 & 0 & * & 0 \end{bmatrix}$$

$$* = -\frac{a-4}{a-6}(3a+3) + (2a-2)$$

\therefore The implied vector equation has a unique solution (the trivial solution) iff

$$\begin{aligned}
& -\frac{a-4}{a-6}(3a+3) + (2a-2) \neq 0 \\
& (a-6) \cdot \left[-\frac{a-4}{a-6}(3a+3) + (2a-2) \right] \neq (a-6) \cdot 0 \\
& -(a-4)(3a+3) + (a-6)(2a-2) \neq 0 \\
& -a^2 - 5a + 24 \neq 0 \\
& a^2 + 5a - 24 \neq 0 \\
& (a+8)(a-3) \neq 0
\end{aligned}$$

\therefore The column vectors of A are linearly independent iff $a \neq -8$ and $a \neq 3$.

Check

$$\begin{bmatrix} 2 & -8 & -2 & 1 & 0 \\ 3 & -8 & 3 & 1 & 0 \\ -1 & -2 & -8 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 5 & 1 & 0 \\ 0 & 1 & 3/2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \leftarrow \text{non trivial solutions.}$$

$$\begin{bmatrix} 2 & 3 & -2 & 1 & 0 \\ 3 & 2 & 3 & 1 & 0 \\ -1 & -2 & 3 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 5 & 1 & 0 \\ 0 & 1 & -4 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \leftarrow \text{non trivial solutions}$$

Just to be safe try $a = 1$

$$\begin{bmatrix} 2 & 1 & -2 & 1 & 0 \\ 3 & 1 & 3 & 1 & 0 \\ -1 & -2 & 1 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 \end{bmatrix} \text{ only trivial solutions}$$

Ex. 3.7

$$\{\vec{v}_1, \vec{v}_2\} \text{ is linearly dependent} \Leftrightarrow \begin{cases} x_1 \vec{v}_1 + x_2 \vec{v}_2 = \vec{0} \\ \text{has non-trivial solutions.} \end{cases}$$

$$\Leftrightarrow \begin{cases} x_1 \vec{v}_1 + x_2 \vec{v}_2 = \vec{0} \\ \text{for some pair of numbers,} \\ x_1, x_2, \text{ not both } 0. \end{cases}$$

$$\Leftrightarrow \begin{cases} \vec{v}_1 = -\frac{x_2}{x_1} \vec{v}_2 \\ \text{and/or } \vec{v}_2 = -\frac{x_1}{x_2} \vec{v}_1 \end{cases}$$

QED

Ex. 3.8 $A = \begin{bmatrix} -4 & 1 & 6 \\ -1 & 1 & 4 \\ 7 & -1 & -3 \end{bmatrix}$

Three vectors span all of \mathbb{R}^3 iff
the vectors are linearly independent
(Thm. 3.4)

$$\begin{bmatrix} -4 & 1 & 6 & 1 & 0 \\ -1 & 1 & 4 & 1 & 0 \\ 7 & -1 & -3 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix}$$

\therefore The column vectors of A are linearly independent, as the only solution to $x_1 \vec{v}_1 + x_2 \vec{v}_2 + x_3 \vec{v}_3$ is trivial solution.

\therefore The column vectors of A do span all of \mathbb{R}^3 .

Ex 3.9

$$\beta = \left\{ \begin{bmatrix} 2 \\ 1 \\ -4 \end{bmatrix}, \begin{bmatrix} -1 \\ 8 \\ 3 \end{bmatrix} \right\}, \text{ A set of two vectors}$$

Can span at most a plane, hence β cannot span \mathbb{R}^3 . Expand β so that it does

span \mathbb{R}^3 .

$$\vec{v}_3 = \begin{bmatrix} 5(2) + 7(1) \\ 5(1) + 7(-8) \\ \text{not } 5(-4) + 7(3) \end{bmatrix} = \begin{bmatrix} 17 \\ -51 \\ 0 \end{bmatrix}$$

independent


$$\begin{bmatrix} 2 & 1 & 17 & 1 & 0 \\ -1 & -8 & -51 & 1 & 0 \\ -4 & 3 & 0 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 & 17 & 1 & 0 \\ -1 & -8 & -51 & 1 & 0 \\ -4 & 3 & 1 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 5 & 1 & 0 \\ 0 & 1 & 7 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

✓
dependent

3.10 $\left\{ \begin{bmatrix} 1 \\ 4 \end{bmatrix}, \begin{bmatrix} -2 \\ 5 \end{bmatrix}, \begin{bmatrix} 3 \\ 5 \end{bmatrix} \right\}$ cannot possibly

be linearly independent because three vectors from \mathbb{R}^2 are never linearly independent (Thm. 3.2)

$\left\{ \begin{bmatrix} 1 \\ 2 \\ -5 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ 4 \\ 2 \end{bmatrix} \right\}$ cannot possibly be linearly independent because it contains $\vec{0}$. To wit:

$$0 \begin{bmatrix} 1 \\ 2 \\ -5 \end{bmatrix} + e^{\pi} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 4 \\ 4 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

↑ non-trivial solution.