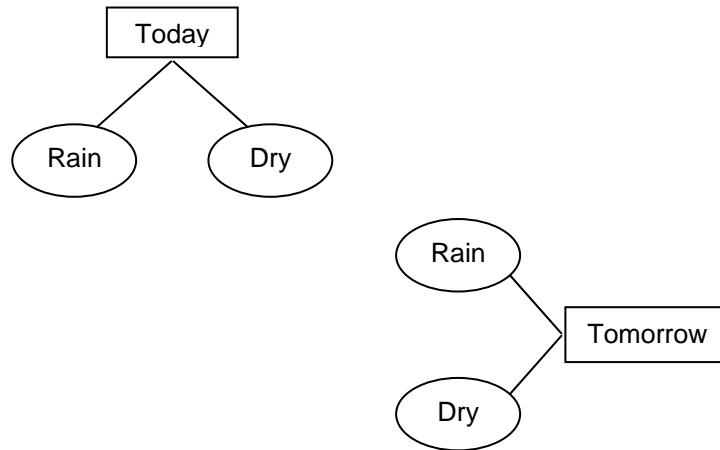


Example 11.1

It rains a lot in Gloomtown. If it rains today, there is a 90% probability that it will rain tomorrow. If it is dry today, there is an 80% chance it will be dry tomorrow. What percentage of days does it rain in Gloomtown?

- a. Let's start by coming up with a transition matrix for this Markov Chain.



- b. Let's familiarize ourselves with the process. What does a state vector represent in the context of this problem?
- c. Let's establish that if it rains today, then the state vector for tomorrow is $P^1 [1, 0]^T$, the state vector two days from now is $P^2 [1, 0]^T$ and the state vector 3 days from now is $P^3 [1, 0]^T$
- d. If it rains today, what are the state vectors for each of the next three days? What about if it's dry today? Then project into the future ... if it rains today, what are the state vectors 50 days from now, 51 days from now, and 52 days from now? What about if it's dry today? What is the steady state vector for this Markov Chain? What does it tell us in the context of this problem?
- e. Let's use eigenvalues to determine the steady state vector for Gloomtown's rainy situation.

Example 11.2

Pretend that Manhattan only has Midtown, the Upper East Side, and the Upper West Side. Suppose that cabbie shifts change only at 6 am and 6 pm. Suppose that a state vector for the distribution of cabs has form $[\text{Midtown}, \text{UES}, \text{UWS}]^T$ and that the transition matrix over each 5 minute interval between 6 am and 6 pm is the matrix P . Find the steady state vector for this model. Suppose that the cabs are evenly distributed at the start of the 6 am shift; how well does the steady state vector predict the distribution of the cabs at the end of that shift?

$$P = \begin{bmatrix} .5 & .3 & .4 \\ .2 & .6 & .1 \\ .3 & .1 & .5 \end{bmatrix}$$



Example 11.3

Explain geometrically why the rotation matrix $R = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$ cannot possibly have any real number eigenvalues for $0 < \theta < \pi$.

Example 11.4

What are bases for the kernel and range of the linear transformation $T(\vec{x}) = A\vec{x}$ where $A = \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}$.

What does this imply must be true about A^2 .

Definitions 11.1-11.4: Stochastic Vectors, Stochastic Matrices, and Markov Chains

A stochastic vector is a vector containing no negative components and whose components sum to 1.

A stochastic matrix is a matrix whose column vectors are stochastic vectors.

Suppose that any given member of a set must be in exactly 1 of a finite number of states at any given time. Suppose further that the state of each member is noted over regular time intervals. Then the stochastic vector $\vec{v}_k = [q_1^{(k)}, q_2^{(k)}, \dots, q_n^{(k)}]$ where $q_i^{(k)}$ is the probability that a given member of the set is in state i at time k is called a state vector.

Suppose that p_{ij} is the probability that a member in state j will transition to state i the next time an account is made. Suppose further that these probabilities do not change over time. Then the sequence $\vec{v}_1, \vec{v}_2, \vec{v}_3, \dots$ is called a Markov Chain.

Furthermore, $\vec{v}_{k+1} = P\vec{v}_k$ where $P = [p_{ij}]_{n \times n}$ and P is called the transition matrix for the Markov Chain.